

**GOVT. POLYTECHNIC BOLANGIR**  
**LESSON PLAN**

<b>Discipline : Automobile</b>	<b>Semester: 5TH</b>	<b>Name of the Teaching Faculty : Faculty 4</b>
<b>Subject : MECHATRONICS</b>	<b>No. of Days / per week class allotted : 4</b>	<b>Semester From date : 15.09.2022 to Date :22.12.2022</b> <b>No. of Weeks : 14</b>
<b>Week</b>	<b>Class Day</b>	<b>Topics</b>
<b>15.9 - 17.9</b>	1st	Definition of Mechatronics
	2nd	Advantages & disadvantages of Mechatronics
	3rd	Application of Mechatronics
	4th	Scope of Mechatronics in Industrial Sector
<b>19.9-24.9</b>	1st	Components of a Mechatronics System
	2nd	Importance of mechatronics in automation
	3rd	Definition of Transducers
	4th	Classification of Transducers
<b>26.9-1.10</b>	1st	Electromechanical Transducers
	2nd	Transducers Actuating Mechanisms
	3rd	Displacement & Positions Sensors , Velocity, motion, force and pressure sensors.
	4th	Temperature and light sensors
<b>10.10-15.10</b>	1st	Machine, Kinematic Link, Kinematic Pair
	2nd	Mechanism, Slider crank Mechanism
	3rd	Gear Drive, Spur gear, Bevel gear, Helical gear, worm gear
	4th	Belt & Belt drive
<b>17.10-22.10</b>	1st	BEARINGS
	2nd	Switches and relay
	3rd	Solenoid
	4th	D.C Motors
<b>24.10-29.10</b>	1st	A.C Motors
	2nd	Stepper Motors
	3rd	Specification and control of stepper motors
	4th	Servo Motors D.C & A.C
<b>31.10-5.11</b>	1st	Introduction
	2nd	Advantages of PLC
	3rd	Selection and uses of PLC
	4th	Architecture basic internal structures
<b>7.11-12.11</b>	1st	Input/output Processing and Programming
	2nd	Mnemonics
	3rd	Master and Jump Controllers
	4th	Master and Jump Controllers
<b>14.11-19.11</b>	1st	NC machines
	2nd	CNC machines
	3rd	CAD/CAM
	4th	CAD
<b>21.11-26.11</b>	1st	CAM
	2nd	Software and hardware for CAD/CAM
	3rd	Functioning of CAD/CAM system
	4th	Features and characteristics of CAD/CAM system

<b>28.11-3.12</b>	1st	Application areas for CAD/CAM
	2nd	ntroduction
	3rd	Machine Structure
	4th	Guideways/Slide ways
<b>5.12-10.12</b>	1st	Introduction and Types of Guideways
	2nd	Factors of design of guideways
	3rd	Spindle drives
	4th	Feed drive
<b>12.12-17.12</b>	1st	Spindle and Spindle Bearings
	2nd	Definition, Function and laws of robotics
	3rd	Types of industrial robots
	4th	Robotic systems
<b>19.12-22.12</b>	1st	Advantages and Disadvantages of robots
	2nd	RIVISION
	3rd	RIVISION
	4th	RIVISION



